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PATENT & TRADEMARK OFFICE

PTO/SB/08A (10-01)
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U.S. Patent and Trademark Office: U.S. DEPARTMENT OF COMMERCE

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INFORMATION DISCLOSURE STATEMENT BY APPLICANT (use as many sheets as necessary)			Complete if Known		
			Application Number	09/153,781	
			Filing Date	9/16/1998	
			First Named Inventor	Louis B. Rosenberg	
			Art Unit	2675	
			Examiner Name	Paul A. Bell	
Sheet	1	of	5	Attorney Docket Number	IMM1P053

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U.S. PATENT DOCUMENTS

Examiner	Cite No. ¹	Document Number	Publication Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document	Pages, Columns, Lines, Where Relevant Passages or Relevant Figures Appear
		Number Kind Code ² (if known)			
FAB TIME 1-5-2002 REMARK OFFICE DOCK		3,220,121	11/30/1965	Cutler	
		3,517,446	6/30/1970	Corlyon et al.	
		3,903,614	9/9/1975	Diamond et al.	
		4,236,325	10/2/1980	Hall et al.	
		4,513,235	4/23/1985	Acklam et al.	
		4,599,070	7/8/1986	Hladky et al.	
		4,708,656	11/24/1987	De Vries et al.	
		4,713,007	12/15/1987	Alban	
		4,891,764	1/2/1990	McIntosh	
		5,019,761	5/28/1991	Kraft	
		5,022,407	6/11/1991	Horch et al.	
		5,240,417	8/31/1993	Smithson et al.	
		5,271,290	12/21/1993	Fischer	
		5,275,174	1/4/1994	Cook	
		5,785,630	7/28/1998	Bobick et al.	
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		5,035,242	7/30/1991	Franklin	
		5,038,089	8/6/1991	Szakaly	
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		5,212,473	5/18/1993	Louis	
	5,466,213	11/14/1995	Hogan		
	5,766,016	6/16/1998	Sinclair		
	5,186,695	2/16/1993	Mangseth et al.		
	6,422,941	7/23/2002	Thomer et al.		
FAB		5,690,582	11/25/1997	Ulrich et al.	

Examiner Signature	Paul Bell	Date Considered	8/7/2003
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**INFORMATION DISCLOSURE
STATEMENT BY APPLICANT**

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Sheet **2** of **5****Complete if Known**

Application Number 09/153,781

Filing Date 9/16/1998

First Named Inventor Louis B. Rosenberg

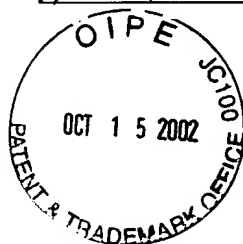
Art Unit 2675

Examiner Name Paul A. Bell

Attorney Docket Number IMM1P053

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PAB		EP	EP0349086	1/3/1990	Visser	

Examiner
Signature*Paul Bell*Date
Considered*8/7/2003*

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Sheet 3 of 5**Complete if Known**

Application Number	09/153,781
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OTHER PRIOR ART -- NON PATENT LITERATURE DOCUMENTS

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<i>PA/B</i>	A1	BAIGRIE, "Electric Control Loading - A Low Cost, High Performance Alternative," Proceedings, pp. 247-254, November 6-8, 1990.	
<i>PA/B</i>	A2	IWATA, "Pen-based Haptic Virtual Environment," 0-7803-1363-1/93 IEEE, pp 287-292, 1993.	
<i>PA/B</i>	A3	RUSO, "The Design and Implementation of a Three Degree of Freedom Force Output Joystick," MIT Libraries Archives 08/14/1990, pp. 1-131, May 1990.	
<i>PA/B</i>	A4	BROOKS et al., "Hand Controllers for Teleoperation - A State-of-the-Art Technology Survey and Evaluation," JPL Publication 85-11; NASA-CR-175890; N85-28559, pp. 1-84, 03/1/1985.	
<i>PA/B</i>	A5	JONES et al., "A perceptual analysis of stiffness," ISSN 0014-4819 Springer International (Springer-Verlag); Experimental Brain Research, Vol. 79, No. 1, pp. 150-156, 1990.	
<i>PA/B</i>	A6	BURDEA et al., "Distributed Virtual Force Feedback, Lecture Notes for Workshop on Force Display in Virtual Environments and its Application to Robotic Teleoperation," 1993 IEEE International Conference on Robotics and Automation, pp. 25-44, 05/02/1993.	
<i>PA/B</i>	A7	SNOW et al., "Model-X Force-Reflecting-Hand-Controller," NT Control No. MPO-17851; JPL Case No. 5348, pp. 1-4, 06/15/1989.	
<i>PA/B</i>	A8	OUH-YOUNG, "Force Display in Molecular Docking," Order No. 9034744, p. 1-369, 1990.	
<i>PA/B</i>	A9	TADROS, "Control System Design for a Three Degree of Freedom Virtual Environment Simulator Using Motor/Brake Pair Actuators, MIT Archive © Massachusetts Institute of Technology, pp. 1-88, February 1990.	
<i>PA/B</i>	A10	CALDWELL et al., "Enhanced Tactile Feedback (Tele-Taction) Using a Multi-Functional Sensory System," 1050-4729/93, pp. 955-960, 1993.	
	A11	ADELSTEIN, "Design and Implementation of a Force Reflecting Manipulandum for Manual Control research," DSC-Vol. 42, Advances in Robotics, Edited by H. Kazerooni, pp. 1-12, 1992.	
	A12	GOTOW et al., "Controlled Impedance Test Apparatus for Studying Human Interpretation of Kinesthetic Feedback," WA11-11:00, pp. 332-337	
	A13	STANLEY et al., "Computer Simulation of Interacting Dynamic Mechanical Systems Using Distributed Memory Parallel Processors," DSC-Vol. 42, Advances in Robotics, pp. 55-61, ASME 1992.	
<i>PA/B</i>	A14	RUSO, "Controlling Dissipative Magnetic Particle Brakes in Force Reflective Devices," DSC-Vol. 42, Advances in Robotics, pp. 63-70, ASME 1992.	

Examiner
Signature*Paul Bell*Date
Considered*2/7/2003*

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STATEMENT BY APPLICANT**

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Sheet 4 of 5**Complete if Known**

Application Number 09/153,781

Filing Date 9/16/1998

First Named Inventor Louis B. Rosenberg

Art Unit 2675

Examiner Name Paul A. Bell

Attorney Docket Number IMM1P053

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OTHER PRIOR ART -- NON PATENT LITERATURE DOCUMENTS

Examiner Initials *	Cite No. ¹	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published.	T ²
PAB	A15	KONTARINIS et al., "Display of High-Frequency Tactile Information to Teleoperators," Telemanipulator Technology and Space Telerobotics, Won S. Kim, Editor, Proc. SPIE Vol. 2057, pp. 40-50, Sep. 7-9, 1993.	
	A16	PATRICK et al., "Design and Testing of A Non-reactive, Fingertip, Tactile Display for Interaction with Remote Environments," Cooperative Intelligent Robotics in Space, Rui J. deFigueiredo et al., Editor, Proc. SPIE Vol. 1387, pp. 215-222, 1990.	
	A17	ADELSTEIN, "A Virtual Environment System For The Study of Human Arm Tremor," Ph.D. Dissertation, Dept. of Mechanical Engineering, MIT, June 1989.	
	A18	BEJCZY, "Sensors, Controls, and Man-Machine Interface for Advanced Teleoperation," Science, Vol. 208, No. 4450, pp. 1327-1335, 1980.	
	A19	BEJCZY, "Generalization of Bilateral Force-Reflecting Control of Manipulators," Proceedings Of Fourth CISM-IFTOMM, Sep. 8-12, 1981.	
	A20	MCAFFEE, "Teleoperator Subsystem/Telerobot Demonstrator: Force Reflecting Hand Controller Equipment Manual," JPL D-5172, pp. 1- 50, A1-A36, B1-B5, C1-C36, January 1988.	
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	A22	JACOBSEN et al., "High Performance, Dexterous Telerobotic Manipulator With Force Reflection," Intervention/ROV '91 Conference & Exposition, Hollywood, Florida, May 21-23, 1991.	
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	A26	HOWE, "A Force-Reflecting Teleoperated Hand System for the Study of Tactile Sensing in Precision Manipulation," Proceedings of the 1992 IEEE International Conference on Robotics and Automation, Nice, France, May 1992.	
	A27	EBERHARDT et al., "OMAR - A Haptic display for speech perception by deaf and deaf-blind individuals," IEEE Virtual Reality Annual International Symposium, Seattle, WA, Sep. 18-22, 1993.	
PAB	A28	RABINOWITZ et al., "Multidimensional tactile displays: Identification of vibratory intensity, frequency, and contactor area," Journal of The Acoustical Society of America, Vol. 82, No. 4, October 1987.	

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Signature

Paul Bell

Date
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Sheet 5 of 5

Complete if Known

Application Number	09/153,781
Filing Date	9/16/1998
First Named Inventor	Louis B. Rosenberg
Art Unit	2675
Examiner Name	Paul A. Bell
Attorney Docket Number	IMM1P053

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PAB	A29	BEJCZY et al., "Kinesthetic Coupling Between Operator and Remote Manipulator," International Computer Technology Conference, The American Society of Mechanical Engineers, San Francisco, CA, August 12-15, 1980.	
	A30	BEJCZY et al., "A Laboratory Breadboard System For Dual-Arm Teleoperation," SOAR '89 Workshop, JSC, Houston, TX, July 25-27, 1989.	
	A31	OUH-YOUNG, "A Low-Cost Force Feedback Joystick and Its Use in PC Video Games," IEEE Transactions on Consumer Electronics, Vol. 41, No. 3, August 1995.	
	A32	MARCUS, "Touch Feedback in Surgery," Proceedings of Virtual Reality and Medicine The Cutting Edge, Sep. 8-11, 1994.	
	A33	BEJCZY, et al., "Universal Computer Control System (UCCS) For Space Telerobots," CH2413-3/87/0000/0318501.00 1987 IEEE, 1987.	
	A34	YAMAKITA et al., "Tele-Virtual Reality of Dynamic Mechanical Model," Proceedings of the 1992 IEEE/RSJ International Conference on Intelligent Robots and Systems, Raleigh, NC, July 7-10, 1992	
↓	A35	NOLL, "Man-Machine Tactile," SID Journal, July/August 1972 Issue.	
PAB			

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Sheet 1 of 6

Application Number	09/153,781
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PAB	BJ	EP	0349086		1/3/1990	Stork Kwant B.V.	
	BK	JP	01-003664		7/19/1990	Taito Corporation	
	BL	JP	02-109714		1/13/1992	Epoch Co. and Key- Planning Co.	
	BM	JP	05-193862		1/27/1995	Sega Corporation	
PAB	BN	JP	04-007371		8/3/1993	Taito Corporation	

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PAB	BO	BAIGRIE, "Electric Control Loading - A Low Cost, High Performance Alternative," Proceedings, pp. 247-254, November 6-8, 1990.	
	BP	IWATA, "Pen-based Haptic Virtual Environment," 0-7803-1363-1/93 IEEE, pp 287-292, 1993.	
	BQ	RUSO, "The Design and Implementation of a Three Degree of Freedom Force Output Joystick," MIT Libraries Archives 08/14/1990, pp. 1-131, May 1990.	
	BR	BROOKS et al., "Hand Controllers for Teleoperation - A State-of-the-Art Technology Survey and Evaluation," JPL Publication 85-11; NASA-CR-175890; N85-28559, pp. 1-84, 03/1/1985.	
	BS	JONES et al., "A perceptual analysis of stiffness," ISSN 0014-4819 Springer International (Springer-Verlag); Experimental Brain Research, Vol. 79, No. 1, pp. 150-156, 1990.	
	BT	BURDEA et al., "Distributed Virtual Force Feedback, Lecture Notes for Workshop on Force Display in Virtual Environments and its Application to Robotic Teleoperation," 1993 IEEE International Conference on Robotics and Automation, pp. 25-44, 05/02/1993.	
	BU	SNOW et al., "Model-X Force-Reflecting-Hand-Controller," NT Control No. MPO-17851; JPL Case No. 5348, pp. 1-4, 06/15/1989.	
	BV	OUH-YOUNG, "Force Display in Molecular Docking," Order No. 9034744, p. 1-369, 1990.	
	BW	TADROS, "Control System Design for a Three Degree of Freedom Virtual Environment Simulator Using Motor/Brake Pair Actuators, MIT Archive © Massachusetts Institute of Technology, pp. 1-88, February 1990.	
	BX	CALDWELL et al., "Enhanced Tactile Feedback (Tele-Taction) Using a Multi-Functional Sensory System," 1050-4729/93, pp. 955-960, 1993.	
	BY	ADELSTEIN, "Design and Implementation of a Force Reflecting Manipulandum for Manual Control research," DSC-Vol. 42, Advances in Robotics, Edited by H. Kazerooni, pp. 1-12, 1992.	
	BZ	GOTOW et al., "Controlled Impedance Test Apparatus for Studying Human Interpretation of Kinesthetic Feedback," WA11-11:00, pp. 332-337	
	CA	STANLEY et al., "Computer Simulation of Interacting Dynamic Mechanical Systems Using Distributed Memory Parallel Processors," DSC-Vol. 42, Advances in Robotics, pp. 55-61, ASME 1992.	
PAB	CB	RUSO, "Controlling Dissipative Magnetic Particle Brakes in Force Reflective Devices," DSC-Vol. 42, Advances in Robotics, pp. 63-70, ASME 1992.	

Examiner Signature	Paul Bell	Date Considered	8/7/2003
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Sheet **4** of **6**

Application Number	09/153,781
Filing Date	September 16, 1998
First Named Inventor	Louis B. Rosenberg, et al.
Art Unit	2675
Examiner Name	Paul A. Bell
Attorney Docket Number	IMM053

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PAB	CC	KONTARINIS et al., "Display of High-Frequency Tactile Information to Teleoperators," Telemanipulator Technology and Space Telerobotics, Won S. Kim, Editor, Proc. SPIE Vol. 2057, pp. 40-50, Sep. 7-9, 1993.	
	CD	PATRICK et al., "Design and Testing of A Non-reactive, Fingertip, Tactile Display for Interaction with Remote Environments," Cooperative Intelligent Robotics in Space, Rui J. deFigueiredo et al., Editor, Proc. SPIE Vol. 1387, pp. 215-222, 1990.	
	CE	ADELSTEIN, "A Virtual Environment System For The Study of Human Arm Tremor," Ph.D. Dissertation, Dept. of Mechanical Engineering, MIT, June 1989.	
	CF	BEJCZY, "Sensors, Controls, and Man-Machine Interface for Advanced Teleoperation," Science, Vol. 208, No. 4450, pp. 1327-1335, 1980.	
	CG	BEJCZY, "Generalization of Bilateral Force-Reflecting Control of Manipulators," Proceedings Of Fourth CISM-IFTOMM, Sep. 8-12, 1981.	
	CH	MCAFFEE, "Teleoperator Subsystem/Telerobot Demonstrator: Force Reflecting Hand Controller Equipment Manual," JPL D-5172, pp. 1- 50, A1-A36, B1-B5, C1-C36, January 1988.	
	CI	MINSKY, "Computational Haptics: The Sandpaper System for Synthesizing Texture for a Force-Feedback Display," Ph.D. Dissertation, MIT, June 1995.	
	CJ	JACOBSEN et al., "High Performance, Dexterous Telerobotic Manipulator With Force Reflection," Intervention/ROV '91 Conference & Exposition, Hollywood, Florida, May 21-23, 1991.	
	CK	SHIMOGA, "Finger Force and Touch Feedback Issues in Dexterous Telemanipulation," Proceedings of Fourth Annual Conference on Intelligent Robotic Systems for Space Exploration, Rensselaer Polytechnic Institute, Sep. 30 - Oct. 1, 1992.	
	CL	IBM Technical Disclosure Bulletin, "Mouse Ball-Actuating Device With Force and Tactile Feedback," Vol. 32, No. 9B, February 1990.	
	CM	TERRY et al., "Tactile Feedback In A Computer Mouse," Proceedings of Fourteenth Annual Northeast Bioengineering Conference, University of New Hampshire, March 10-11, 1988.	
	CN	HOWE, "A Force-Reflecting Teleoperated Hand System for the Study of Tactile Sensing in Precision Manipulation," Proceedings of the 1992 IEEE International Conference on Robotics and Automation, Nice, France, May 1992.	
PAB	CO	EBERHARDT et al., "OMAR - A Haptic display for speech perception by deaf and deaf-blind individuals," IEEE Virtual Reality Annual International Symposium, Seattle, WA, Sep. 18-22, 1993.	

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PCB	CP	RABINOWITZ et al., "Multidimensional tactile displays: Identification of vibratory intensity, frequency, and contactor area," Journal of The Acoustical Society of America, Vol. 82, No. 4, October 1987.	
	CQ	BEJCZY et al., "Kinesthetic Coupling Between Operator and Remote Manipulator," International Computer Technology Conference, The American Society of Mechanical Engineers, San Francisco, CA, August 12-15, 1980.	
	CR	BEJCZY et al., "A Laboratory Breadboard System For Dual-Arm Teleoperation," SOAR '89 Workshop, JSC, Houston, TX, July 25-27, 1989.	
	CS	OUH-YOUNG, "A Low-Cost Force Feedback Joystick and Its Use in PC Video Games," IEEE Transactions on Consumer Electronics, Vol. 41, No. 3, August 1995.	
	CT	MARCUS, "Touch Feedback in Surgery," Proceedings of Virtual Reality and Medicine The Cutting Edge, Sep. 8-11, 1994.	
	CU	BEJCZY, et al., "Universal Computer Control System (UCCS) For Space Telerobots," CH2413-3/87/0000/0318501.00 1987 IEEE, 1987.	
	CV	YAMAKITA et al., "Tele-Virtual Reality of Dynamic Mechanical Model," Proceedings of the 1992 IEEE/RSJ International Conference on Intelligent Robots and Systems, Raleigh, NC, July 7-10, 1992	
	CW	NOLL, "Man-Machine Tactile," SID Journal, July/August 1972 Issue.	
	CX	AUKSTAKALNIS et al., "Silicon Mirage: The Art and Science of Virtual Reality," ISBN 0-938151-82-7, pp. 129-180, 1992.	
	CY	EBERHARDT et al., "Including Dynamic Haptic Perception by The Hand: System Description and Some Results," DSC-Vol. 55-1, Dynamic Systems and Control: Volume 1, ASME 1994.	
	CZ	GOBEL et al., "Tactile Feedback Applied to Computer Mice," International Journal of Human-Computer Interaction, Vol. 7, No. 1, pp. 1-24, 1995.	
	DA	PIMENTEL et al., "Virtual Reality: through the new looking glass," 2 nd Edition; McGraw-Hill, ISBN 0-07-050167-X, pp. 41-202, 1994.	
	DB	"Cyberman Technical Specification," Logitech Cyberman SWIFT Supplement, 4/5/1994.	
PCB	DC	OUHYOUNG et al., "The Development of A Low-Cost Force Feedback Joystick and Its Use in the Virtual Reality Environment," Proceedings of the Third Pacific Conference on Computer Graphics and Applications, Pacific Graphics '95, Seoul, Korea, 21-24 August 1995.	

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PAB	DD	KACZMAREK et al., "Tactile Displays," Virtual Environment Technologies.	
PAB	DE	SCANNELL, "Taking a Joystick Ride," Computer Currents, Boston Edition, Vol. 9, No. 11, November 1994	

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